

Industrial



SERVO DRIVES FOR COMMERCIAL & INDUSTRIAL

2019 Industrial Products











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opley Controls delivers high performance motion solutions to a wide range of industries including semiconductor, life sciences, test systems, automated assembly, and COTS military. An ISO 9001:2015 company, Copley produces products of the highest quality in state-of-the-art manufacturing facilities in the US and China. Copley drives carry a full 2-year warranty.

With over 35 years of experience in OEM partnerships, Copley's application team combines with R&D to deliver world-class, highly responsive support. Our global commitment is backed with sales offices and local technical resources in the US, Europe and Asia.

From networked servo and stepper drives to traditional torque amplifiers, Copley has the solution for your system architecture. Both AC and DC powered drives with flexible packaging options are offered in the 100 W - 6 kW power range. They provide a comprehensive range of motor feedback interfaces, advanced tuning and commutation algorithms that maximize motor performance.

As part of Analogic Corporation, Copley Controls has the buying power and resources to compete long term in the global marketplace. Our customer commitment has stood the test of time with many models in production for well over three decades.



Servo & Stepper Panel Drives

Copley offers a comprehensive range of digital drives for brush, brushless and stepper motors. High power density panel-mount and PCB-mount packages deliver installation flexibility. A complete set of feedback options are provided. Both AC and DC powered versions are available.

Industrial servo drives are full featured drives with connectors, EMI shielding and PE grounding which can withstand the varied range of industrial conditions. Ruggedized versions of select servo drives are available for COTS military applications.

Configuration & Control Software

Copley drive configuration software, CME is highly intuitive and incorporates powerful diagnostic tools. An easy-to-use Indexer is built in. For more complex applications, Copley Programming Language (CPL) a flexible high-level language is provided with powerful editing and debugging capabilities.

Network software tools make multi-axis control system commissioning fast and simple. Proven Copley source code for the control and management of both EtherCAT and CANopen networks facilitates application implementation. Migration from CANopen to EtherCAT is straightforward and seamless.





PC Architecture

Copley drives connect seamlessly to both CANopen and EtherCAT - the networks of choice for PC-based systems. Copley drives are integrated into third-party software tools such as CoDeSys, enabling complete PC-based multi-axis motion control solutions. Copley also supports simple ASCII and serial binary protocols over RS-232 with serial multidrop using CAN.

Motion Controllers

Both the traditional ±10 V and PWM current/velocity command interfaces are built-in on all drives. For Delta Tau motion controllers, MACRO drives enable an optimal motion control system solution.

PLC Systems

Control via PLCs is facilitated by a step/direction interface as well as I/O selection and execution of predefined indexer programs. An ASCII command interface is also available.

Field Oriented Control

- Optimal orientation of magnetic field
- Motors run faster and cooler

Servo & PWM Performance

- High-bandwidth nested loops
- Biquad filter for notch or low pass filters
- High-efficiency dynamic PWM
- Edge filter accessories for low emissions

Stepper Technology

- Smooth, low audible noise
- Precision Microstepping, low resonance
- Servo mode for closed loop control
- Detent torque compensation

The Copley PLUS Advantage

PLUS drives support EtherCAT or CANopen and offer expanded feedback options. Metal enclosures ensure the highest level of noise immunity. Multi-axis versions deliver the lowest cost per node. PLUS drives feature high resolution A/D converters for optimal current control as well as fast, hardware-based position capture and set point trigger output.

Design Standards

- UL/IEC 61010-1, 3rd Edition
- UL/IEC 61800-5-1
- UL/IEC 61800-5-2
- IEC 61800-3
- EN 55011
- EN 61000-6-1

STO (Safe Torque Off)

The STO capability of PLUS panel drives eliminates the expensive contactors and complex wiring traditionally used in safety critical applications. Two independent inputs are provided to implement the STO function and facilitate the system conformance to *SIL* 3 (IEC 61800-5-2) and Category 3 PL d (ISO 13849-1).



Xenus - Servo

Xenus panels are available in two AC line operated compact packages delivering power up to 6 kW. A +24 Vdc input powers control circuits, ensuring keep-alive operation. Control interfaces include CANopen as well as traditional analog commands. Incremental encoder feedback is standard with optional resolver and analog encoder interfaces.

| | Model | Vac | lc | lp |
|---------------------|---------------------|---------|-------|--------|
| XTL | XTL-230-18 | 100-240 | 6 | 18 |
| | XTL-230-36 | 100-240 | 12 | 36 |
| | XTL-230-40 | 100-240 | 20 | 40 |
| | | | | _ |
| | | | Sin/C | os: -S |
| | Model | Vac | Sin/C | os: -S |
| XSJ | Model XSJ-230-06 | | | |
| XSJ Micro | | Vac | lc | lp |

Accelnet - Servo

Accelnet panels are available in two DC-powered panel-mounted packages. Control interfaces include CANopen as well as traditional analog commands. Incremental encoder feedback is standard with optional resolver and analog encoder interfaces.

| | Model | Vdc | lc | lр |
|--------------|--|----------------------------------|-----------------------|---------------------|
| ADP | ADP-055-18 | 20-55 | 6 | 18 |
| | ADP-090-09 | 20-90 | 3 | 9 |
| | ADP-090-18 | 20-90 | 6 | 18 |
| | ADP-090-36 | 20-90 | 12 | 36 |
| | ADP-180-09 | 20-180 | 3 | 9 |
| | ADP-180-18 | 20-180 | 6 | 18 |
| | ADP-180-30 | 20-180 | 15 | 30 |
| | | | | |
| | | | Sin/C | os: -S |
| | Model | Vdc | Sin/C | os: -S Ip |
| ACJ | Model ACJ-055-09 | Vdc 20-55 | | |
| ACJ Micro | | | lc | lр |
| | ACJ-055-09 | 20-55 | Ic | lp |
| | ACJ-055-09 ACJ-055-18 | 20-55 20-55 | 3 6 | Ip 9 18 |
| | ACJ-055-09 ACJ-055-18 ACJ-090-03 | 20-55 20-55 20-90 | 3 6 1 | Ip 9 18 3 |
| | ACJ-055-09 ACJ-055-18 ACJ-090-03 ACJ-090-09 | 20-55 20-55 20-90 20-90 | 3 6 1 3 6 | 9 18 3 9 |

Stepnet - Stepper

The Stepnet panel family comprises both AC and DC powered versions. Control interfaces include CANopen as well as traditional Step/Direction inputs. Microstepping delivers smooth, low-resonance performance. In Servo Mode, with encoder feedback, stepper motors run quietly and can operate at higher speeds without stalling.

| Model | Vac | lc | lр |
|--------------|--|--|---|
| STX-115-07 | 100-120 | 5 | 7 |
| STX-230-07 | 200-240 | 5 | 7 |
| Model | Vdc | lc | lр |
| STP-075-07 | 20-75 | 5 | 7 |
| 011 -07 5-07 | 20-13 | J | , |
| | STX-115-07 STX-230-07 Model | STX-115-07 100-120 STX-230-07 200-240 Model Vdc | STX-115-07 100-120 5 STX-230-07 200-240 5 Model Vdc Ic |

Control Modes

- Indexer, Point-to-Point, PVT
- Camming, Gearing, Position, Velocity, Torque

Command Interface

- CANopen
- ASCII, Serial Binary and discrete I/O
- Stepper commands
- ±10 V Position/Velocity/Torque command
- PWM Velocity/Torque command
- Master Encoder (Gearing/Camming)

Communications

- CANopen
- RS-232

Feedback

- Digital quad A/B encoder
- Digital Halls
- Aux. encoder / encoder out
- Analog Sin/Cos encoder (-S option)
- Dual loop feedback

Firmware Features (XTL, XSJ, ADP)

- BiSS -C Unidirectional, SSI (Consult factory)
- 32-bit floating point multi loop filters
- Frequency analysis tools

I/O - Digital

■ 9-14 inputs, 3-4 outputs

Accessories

- XTL External regen resistors XTL-RA-XX
- XTL, XSJ External edge filter XTL-FA-01

Dimensions: mm (in)

- **XTL** 192 x 142 x 65 (7.6 x 5.6 x 2.6)
- **XSJ** 126 x 89 x 53 (5.0 x 3.5 x 2.1)
- ADP 168 x 99 x 31 (6.6 x 3.9 x 1.2)
- ACJ 97 x 64 x 33 (3.8 x 2.5 x 1.3)
- **STX** 146 x 119 x 55 (5.7 x 4.7 x 2.2)
- **STP** 136 x 84 x 42 (5.4 x 3.3 x 1.7)





Xenus XTL AFS









Stepnet STX



Stepnet STP

Xenus^{PLUS} - Servo

Xenus^{PLUS} AC powered drives are available in both EtherCAT and CANopen versions. Multi-axis models deliver optimal cost per node. A wide range of absolute encoder interfaces are built-in, including EnDat, BiSS, Absolute A and SSI. STO functionality reduces system cost in safety critical applications.

| | Model | Vac | lc | lр |
|----------|------------|--------------|-------|------|
| XEC, XPC | X*C-230-09 | 100-240 | 3 | 9 |
| | X*C-230-12 | 100-240 | 6 | 12 |
| | X*C-230-15 | 100-240 | 7.5 | 15 |
| | | Res | olver | : -R |
| | Model | Vac | lc | lр |
| XEL, XPL | X*L-230-18 | 100-240 | 6 | 18 |
| | X*L-230-36 | 100-240 | 12 | 36 |
| | X*L-230-40 | 100-240 | 20 | 40 |
| | | Resolver: -R | | : -R |
| | Model | Vac | lc | lр |
| XE2, XP2 | X*2-230-20 | 100-240 | 10 | 20 |
| 2-Axis | | Res | olver | : -R |

Accelnet^{PLUS} - Servo

Accelnet PLUS sets new levels of performance and is available in both EtherCAT and CANopen versions. Multi-axis models deliver optimal cost per node. A wide range of absolute encoder interfaces are built-in, including EnDat, BiSS, Absolute A and SSI. Higher-resolution current loops enable Accelnet PLUS to meet the needs of the most demanding applications. STO functionality reduces system cost in safety critical applications.

| | Model | Vdc | lc | lр |
|-------------------|------------|--------------|--------|-------|
| BEL, BPL | B*L-090-06 | 14-90 | 3 | 6 |
| | B*L-090-14 | 14-90 | 7 | 14 |
| | B*L-090-30 | 14-90 | 15 | 30 |
| | | Res | solver | :: -R |
| | Model | Vdc | lc | lр |
| BE2, BP2 | B*2-090-06 | 14-90 | 3 | 6 |
| 2-Axis | B*2-090-14 | 14-90 | 7 | 14 |
| | B*2-090-20 | 14-90 | 10 | 20 |
| | | Resolver: -R | | :: -R |
| | Model | Vdc | lc | lр |
| AEZ, APZ Micro | A*Z-090-50 | 14-90 | 25 | 50 |

Stepnet^{PLUS} - Stepper

Stepnet^{PLUS} sets new levels of performance and is available in both EtherCAT and CANopen versions. Multi-axis models provide optimal cost per node. Microstepping delivers smooth, low-resonance performance. In Servo Mode, with encoder feedback, stepper motors run quietly and can operate at higher speeds without stalling. A wide range of absolute encoder interfaces are built-in, including EnDat, BiSS, Absolute A and SSI.

| | Model | Vdc | lc | lр |
|--------------------|-------------------------|------------------|-------------|-------------|
| TEL | TEL-090-07 | 14-90 | 5 | 7 |
| | TEL-090-10 | 14-90 | 10 | 10 |
| | | | | |
| | Model | Vdc | lc | lр |
| TE2, TP2 | Model T*2-090-07 | Vdc 14-90 | Ic 5 | Ip 7 |
| TE2, TP2 2-Axis | | | | 7 10 |

Control Modes

- CPL, Indexer, Point-to-Point, PVT, PT, CSP, CST, CSV
- Camming, Gearing
- Position, Velocity, Torque

Command & Communications

- EtherCAT CoE DS-402 (XEC, XEL, XE2, BEL, BE2, TEL, TE2, AEZ)
- CANopen DS-402 (XPC, XPL, XP2, BPL, BP2, TP2, APZ)
- RS-232, ASCII & Serial Binary
- Step/Direction, Step Up/Step Down
- ±10 V Position/Velocity/Torque
- PWM Velocity/Torque
- Master encoder
- Dual Analog UV command (XPL,XEL)

Feedback

- Incremental encoder & digital Halls
- BiSS, SSI, Absolute A, EnDat encoders
- Panasonic, Tamagawa, Sanyo Denki
- Analog Sin/Cos encoder
- Resolver (-R option)
- Aux. encoder / encoder out
- Dual Absolute (Single axis servo drives only)

Functional Safety

STO Certified (Except X*L)

FPGA Firmware Features

- 32-bit floating point multi loop filters
- Frequency analysis tools
- Hardware pulse at position
- Cross coupling (Dual axis drives)
- High speed position capture
- Count divider

I/O - Digital

- Digital X*C: 11 inputs, 5 outputs
- Digital X*L: 15 inputs, 6 outputs
- Digital X*2: 22 inputs, 7 outputs
- Digital B*L, TEL: 11 inputs, 4 outputs
- Digital B*2: 18 inputs, 7 outputs
- Digital T*2: 24 inputs, 7 outputs
- Digital A*Z: 7 inputs, 6 outputs
- Analog X*C, B**, T*2: 1, 12-bit input
- Analog X*L: 2, 16-bit inputs; 1, 12-bit output
- Analog X*2: 2, 14-bit inputs
- Analog A*Z: 1, 16-bit input

Regen

- X*C, X*2: Built-in regen resistor
- X*L, X*2: External regen resistor accessory XTL-RA-XX

Dimensions: mm (in)

- **X*C** 191 x 116 x 54 (7.5 x 4.6 x 2.1)
- X*L 201 x 140 x 59 (7.9 x 5.5 x 2.3)
- **X*2** 235 x 138 x 91 (9.3 x 5.4 x 3.6)
- **B*L** 129 x 87 x 50 (5.1 x 3.4 x 2.0)
- **B*2** 172 x 119 x 44 (6.8 x 4.7 x 1.7)
- **TEL** 129 x 87 x 50 (5.1 x 3.4 x 2.0)
- **T*2** 172 x 119 x 50 (6.8 x 4.7 x 2.0)
- **A*Z** 112 x 53 x 42 $(4.4 \times 2.1 \times 1.7)$
 - * Indicates E -EtherCAT and P -CANopen



Accelnet^{PLUS} AEZ



Xenus^{PLUS} XEL



Xenus^{PLUS} XE2



Xenus^{PLUS} XEC



Accelnet^{PLUS} BE2 Stepnet^{PLUS} TE2



Accelnet^{PLUS} BEL Stepnet^{PLUS} TEL

MACRO Drives - Servo

MACRO facilitates the powerful combination of Delta Tau controllers and Copley drives. Both AC powered Xenus^{PLUS} (1 & 2-axis) and DC powered Accelnet^{PLUS} drives are available. High resolution A/D converters ensure optimal current loop performance. MACRO drives incorporate the STO capability and interface to a comprehensive range of encoders.

| | Model | Vac | lc | lр |
|--------|--------------|---------|-------|------|
| XML | XML-230-18 | 100-240 | 6 | 18 |
| | XML-230-36 | 100-240 | 12 | 36 |
| | XML-230-40 | 100-240 | 20 | 40 |
| | | Res | olver | : -R |
| | Model | Vac | lc | lр |
| XM2 | XM2-230-20 | 100-240 | 10 | 20 |
| 2-Axis | Resolver: -R | | | : -R |
| | Model | Vdc | lc | lр |
| BML | BML-090-06 | 14-90 | 3 | 6 |
| | BML-090-14 | 14-90 | 7 | 14 |
| | BML-090-30 | 14-90 | 15 | 30 |
| | | | | |

Command & Communications

- MACRO (fiber optic)
- XML Analog UV command
- Digital UV command
- Serial Network UV command

Feedback

- Incremental encoder, digital Halls
- BiSS, SSI, Absolute A, EnDat encoders
- Panasonic, Tamagawa, Sanyo Denki
- Analog Sin/Cos encoder
- Resolver (XML, XM2 -R option)
- Aux. encoder / encoder out
- Dual Absolute (Single axis drives)

Functional Safety

STO Certified (XM2, BML)

I/O

- Digital XML: 15 inputs, 6 outputs
- Digital XM2: 22 inputs, 7 outputs
- Digital BML: 11 inputs, 4 outputs
- Analog XML: 2, 16-bit inputs;
 1, 12-bit input; 1, 12-bit output
- Analog XM2: 2, 14-bit inputs
- Analog BML: 1, 12-bit input

Regen

- XML: External regen resistor accessory XTL-RA-XX
- XM2: Built-in regen resistor

Dimensions: mm (in)

- **XML** 201 x 140 x 59 (7.9 x 5.5 x 2.3)
- **XM2** 235 x 138 x 91 (9.2 x 5.4 x 3.6)
- **BML** 129 x 87 x 50 (5.1 x 3.4 x 2.0)

Custom Drives

Copley provides competitive advantage to the OEM by tailoring designs to precisely fit the application. Copley development engineers and application team will work closely with you to define your requirements and deliver a just-right solution.

Customization can be as simple as special I/O functions or as complex as a multi-axis drive package. Software customization includes application-specific indexer functions, control filters and specialized analysis and diagnostic tools.

In addition to customized drives, Copley's motion subsystem design and manufacturing capability can significantly reduce time to market while freeing-up key OEM resources to focus on core design issues. Copley's expertise in power and thermal management as well as experience in the accelerated life test of complex subsystems guarantee lowered cost of ownership. Optimized motion subsystem design ensures the highest level of performance in the smallest footprint.







Xenus^{PLUS} XM2



AccelnetPLUS BML



Distributors for Australia & New Zealand MOTION TECHNOLOGIES PTY LIMITED



24/22-30 Northumberland Road Caringbah NSW 2229 Australia Phone: (02) 9524 4782

sales@motiontech.com.au www.motiontech.com.au

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