Dual Motion
Size 14 Linear/Rotary Actuators
Axially move components to their insertion positions and then rotate them.
Based on unique, patented designs and incorporate proven motor technology. Units simplify product development by replacing what would otherwise be far more bulky and complex mechanisms.
Another feature of this design is to provide an electric motor in which linear and rotary motions are controllable independently of one another.

For a rotary/linear motor, it is desirable that the linear and rotary motions be controllable independently of one another. These devices can be run using a standard two axis stepper motor driver. Performance can be enhanced using chopper and/or microstepping drives.
Encoders available. US Digital E5 for linear, E6 for rotary.


| Linear Travel / Step |  | Load Limit |  | Order Code I.D. |
| :---: | :---: | :---: | :---: | :---: |
| inches | mm | lbs | N |  |
| 0.00006 | 0.0015** | 10 | 44.4 | U |
| $0.000098^{*}$ | 0.0025 | 10 | 44.4 | AA |
| 0.00012 | $0.0030^{*}$ | 15 | 67 | N |
| 0.00019* | 0.005 | 15 | 67 | AB |
| 0.00024 | $0.0061 *$ | 15 | 67 | K |
| 0.00039* | 0.01 | 15 | 67 | AC |
| 0.00048 | $0.0121^{*}$ | 15 | 67 | J |
| $0.00078{ }^{*}$ | 0.02 | 15 | 67 | AD |
| $0.00157^{*}$ | 0.04 | 15 | 67 | AE |


| 35000 Series: $0.9{ }^{\circ}$ Step Angle |  |  |  |  |
| :---: | :---: | :---: | :---: | :---: |
| Linear Travel / Step |  | Load Limit |  | Order Code I.D. |
| inches | mm | lbs | N |  |
| 0.00003 | $0.00076^{*}$ | 10 | 44.4 | BP |
| 0.00005* | 0.00125 | 10 | 44.4 | AY |
| 0.00006 | $0.0015^{*}$ | 15 | 67 | U |
| 0.000098* | 0.0025 | 15 | 67 | AA |
| 0.00012 | $0.0030^{*}$ | 15 | 67 | N |
| 0.00019* | 0.005 | 15 | 67 | AB |
| 0.00024 | $0.0061^{*}$ | 15 | 67 | K |
| 0.00039* | 0.01 | 15 | 67 | AC |
| 0.00079* | 0.02 | 15 | 67 | AD |

VValues tuncated. Standard motors are Class Brated for maximum temperature of $130^{\circ} \mathrm{C}$.

| LR | 35 | H | H | 4 |  | J | 05 | 910 |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| Prefix <br> LR= Linear/Rotary | Series Number Designation $35=35000$ | $\begin{gathered} \text { Rotary Step } \\ \text { Angle } \\ \mathbf{H}=1.8^{\circ} \\ \mathbf{K}=0.9^{\circ} \\ \mathbf{M}=1.8^{\circ} \\ \text { Double } \\ \text { Stack } \\ \mathbf{P}=0.9^{\circ} \\ \text { Double } \\ \text { Stack } \end{gathered}$ | $\begin{gathered} \text { Linear } \\ \text { Step } \\ \text { Angle } \\ \mathrm{H}=1.8^{\circ} \\ \mathrm{K}=0.9^{\circ} \end{gathered}$ | $\begin{gathered} \text { Coils } \\ 4= \\ \text { Bipolar } \\ \text { (4 wire) } \\ 6= \\ \text { Unipolar } \\ (6 \text { wire) } \end{gathered}$ |  | $0.9^{\circ}$ Step Angle <br> Code ID Resolution <br> Travel/Step <br> $\mathrm{BP}=.00003$-in $(.00076)$ <br> $\mathrm{AY}=.00005-\mathrm{in}(.00125)$ <br> $\mathrm{U}=.00006-\mathrm{in}(.0015)$ <br> $\mathrm{AA}=.000098-$-in $(.0025)$ <br> N$=.00012-\mathrm{in}(.0030)$ | Voltage $05=$ 5 VDC $12=$ 12 VDC $\mathrm{SP}=$ Mixed Votages Custom avalade | Suffix <br> Stroke <br> Example: <br> $-910=1-\mathrm{in}$ $(26 \mathrm{~mm})$ <br> $-\mathrm{XXX}=$ <br> Proprietary suffix assigned to a specific customer application. The identifier can apply to either a standard or custom part. |

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Dual Motion
Size 17 Linear/Rotary Actuators

Provide linear and rotary motions, controllable independently of one another
For a rotary/linear motor, it is desirable that the linear and rotary motions be controllable independenty of one another. These devices can be run using a standard two axis stepper motor driver. Performance can be enhanced using chopper and/or microstepping drives.

The actuators are based on unique, patented designs and incorporate proven motor technology. These units simplify product development by replacing wh would otherwise be far more bulky and complex mechanisms.

Encoders available. US Digital E5 for linear, E6 for rotary.


| Stroke | Dim. "A" | Suffix $\#$ | M4x0.7 Thread |
| :---: | :---: | :---: | :---: |
| $0.500(12.7)$ | $3.9(99.3)$ | -905 | -805 |
| $1.00(25.4)$ | $4.409(112.0)$ | -910 | -810 |
| $2.00(50.8)$ | $5.409(137.4)$ | -920 | -820 |
| $4.00(101.6)$ | $7.409(188.2)$ | -925 | -825 |

## Standard strokes available: <br> 



NOTE:All chopper drive curves were created with a 5 volt motor and a 40 volt power supply.
Ramping can increase the performance ofa motor either by increasing the top speed or geting a heavier load accelerated up to speed faster. Also, decceleation can be
Lsed to topo the motor without vereshoot.
With $L$ R drives peak force and speeds are reduced, using a unipolar drive will yeld a further $30 \%$ force reeuccion.

Identifying the Series 43000 Series Dual Motion Part Number Codes when Ordering

| Identifying the Series 43000 Series Dual Motion Part Number Codes when Ordering |  |  |  |  |  |  |  |  |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| LR | 43 | H | H | 4 |  | J | 05 | 910 |
| Prefix $L R=$ Linear/Rotary | $\begin{gathered} \text { Series } \\ \text { Number } \\ \text { Designation } \\ 43=43000 \end{gathered}$ | $\begin{gathered} \text { Rotary Step } \\ \text { Angle } \\ \mathrm{H}=1.8^{\circ} \\ \mathrm{K}=0.9^{\circ} \\ \mathrm{M}=1.8^{\circ} \\ \text { Double } \\ \text { Stack } \\ \mathrm{P}=0.9^{\circ} \\ \text { Double } \\ \text { Stack } \end{gathered}$ | $\begin{gathered} \text { Linear } \\ \text { Step } \\ \text { Angle } \\ \mathrm{H}=1.8^{\circ} \\ \mathrm{K}=0.9^{\circ} \end{gathered}$ | $\begin{gathered} \text { Coils } \\ 4= \\ \text { Bipolar } \\ \text { (4wire) } \\ 6= \\ 6= \\ \text { Unipolar } \\ (6 \text { wire) } \end{gathered}$ |  |  | Voltage $05=$ 5 VDC $12=$ 12 VDC SP $=$ Mixed Voltages Custom V avaiable | Suffix Stroke Example: -910 $=1$-in ( 26 mm ) $-x X X=$ <br> Proprietary suffix assigned to a specific customer application. The identifier can apply to either a standard or custom part. |


| 43000 Series: $1.8{ }^{\circ}$ Step Angle |  |  |  |  |
| :---: | :---: | :---: | :---: | :---: |
| Linear Travel / Step |  | Load Limit |  | Order Code I.D. |
| inches | mm | lbs | N |  |
| 0.00012 | $0.003^{*}$ | 30 | 133 | N |
| 0.000125 | $0.0031 *$ | 30 | 133 | 7 |
| 0.00015625 | 0.0039* | 30 | 133 | P |
| 0.00019* | 0.005 | 30 | 133 | AB |
| 0.00024 | 0.0060* | 30 | 133 | K |
| 0.00025 | $0.0063^{*}$ | 30 | 133 | 9 |
| 0.0003125 | 0.0079* | 50 | 222 | A |
| 0.00039* | 0.01 | 50 | 222 | AC |
| 0.00048 | $0.0121^{*}$ | 50 | 222 | J |
| 0.0005 | $0.0127^{*}$ | 50 | 222 | 3 |
| 0.000625 | $0.0158^{*}$ | 50 | 222 | B |
| $0.00098{ }^{*}$ | 0.025 | 50 | 222 | AQ |
| 0.00096 | $0.0243^{*}$ | 50 | 222 | Q |
| 0.00125 | $0.0317^{*}$ | 50 | 222 | c |
| 0.00196* | 0.05 | 50 | 222 | BH |
| 0.00192 | $0.0487^{*}$ | 50 | 222 | R |
| 0.0025 | 0.0635 | 50 | 222 | Y |
| 0.00375 | 0.0953* | 50 | 222 | AG |
| 0.005 | 0.127 | 50 | 222 | Z |


| 43000 Series: $0.9^{\circ}$ Step Angle |  |  |  |  |
| :---: | :---: | :---: | :---: | :---: |
| Linear Travel / Step |  | Load Limit |  | Order Code I.D. |
| inches | mm | lbs | N |  |
| 0.00006 | 0.0015* | 30 | 133 | U |
| 0.0000625 | $0.0016^{*}$ | 30 | 133 | BB |
| 0.00007825 | 0.00198* | 30 | 133 | V |
| 0.000098* | 0.0025 | 30 | 133 | AA |
| 0.00012 | $0.003^{*}$ | 30 | 133 | N |
| 0.000125 | $0.0031^{*}$ | 30 | 133 | 7 |
| 0.00015625 | $0.0039^{*}$ | 50 | 222 | P |
| 0.00019* | 0.005 | 50 | 222 | AB |
| 0.00024 | $0.0060^{*}$ | 50 | 222 | K |
| 0.00025 | $0.0063^{*}$ | 50 | 222 | 9 |
| 0.0003125 | 0.0079* | 50 | 222 | A |
| 0.00049* | 0.0125 | 50 | 222 | BG |
| 0.00048 | $0.0121^{*}$ | 50 | 222 | J |
| 0.000625 | $0.0158^{*}$ | 50 | 222 | B |
| $0.00098 *$ | 0.025 | 50 | 222 | AQ |
| 0.00096 | $0.0243^{*}$ | 50 | 222 | Q |
| 0.00125 | $0.0317^{*}$ | 50 | 222 | c |
| 0.001875 | $0.0476^{*}$ | 50 | 222 | AF |
| 0.0025 | 0.0635 | 50 | 222 | Y |

*Values tuncated. Standard motors are Class B rated for maximum temperature of $130^{\circ} \mathrm{C}$.

Dimensions $=(m m)$ inches


| Stroke | Dim. "A" | Suffif | M4x0.7Trread |
| :---: | :---: | :---: | :---: |
| $0.500(12.7)$ | $3.9(99.3)$ | -905 | -805 |
| $1.00(25.4)$ | $4.409(112.0)$ | -910 | -810 |
| $2.00(55.8)$ | $5.409(137.4)$ | -920 | -820 |
| $4.00(101.6)$ | $7.409(188.2)$ | -925 | -825 |




## FORCE vs. LINEAR VELOCITY

- Chopper
- Bipolar
- 100\% Duty Cycle
- 8:1 Motor Coil to Drive Supply Voltage


[^0]Ramping can increase the pefformance of a motor e ither by increasing the top speed or geting a heavier load accelerated up to speed faster. Also,
deceieration can bea used tostop the motr wito tovershoot With LR drives peak force and speeds are reduced, ssing a unipolar drive will yield a turther $30 \%$ force reduction.


[^0]:    IOTE:All chopper drive curves were created with a 5 volt motor and 40 volt power suply

