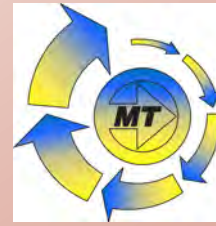


SRAC



AC Input Pulse Direction Stepper Drive

SRAC series stepper drives are based on current PID control algorithm. It is a kind of economical, compact and convenient setup drive.

SRAC series drives can be drove with AC power input, compared with traditional DC power input drives, it has some advantages like larger torque at high-speed; low noise; low vibration, etc. All the parameters can be configured by DIP switches and rotary switch on the drive.

Advanced Current Control
Anti-Resonance
Torque Ripple Smoothing

Microstep Emulation
Optional ac input voltage of 120 v / 220 v switch

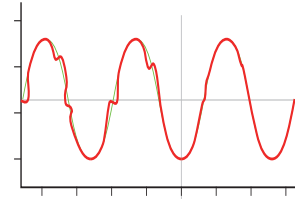


MOONS'
moving in better ways

Features

Anti-Resonance/Electronic Damping

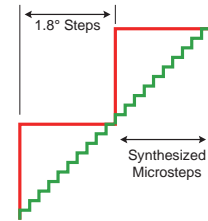
Step motor systems have a natural tendency to resonate at certain speeds. The SRAC drive automatically calculates the system's natural frequency and applies damping to the control algorithm. This greatly improves midrange stability, allows for higher speeds, greater torque utilization and also improves settling times.



Delivers better motor performance and higher speeds

Microstep Emulation

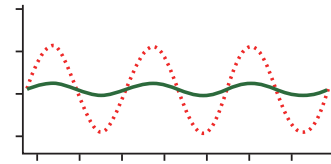
With Microstep Emulation, low resolution systems can still provide smooth motion. The drive can take low-resolution step pulses and create fine resolution micro-step motion.



Delivers smoother motion in any application

Torque Ripple Smoothing

All step motors have an inherent low speed torque ripple that can affect the motion of the motor. By analyzing this torque ripple the system can apply a negative harmonic to negate this effect, which gives the motor much smoother motion at low speed.



Delivers smoother motion at lower speeds

Command Signal Smoothing

Command Signal smoothing can soften the effect of immediate changes in velocity and direction, making the motion of the motor less jerky. An added advantage is that it can reduce the wear on mechanical components.



Improves overall system performance

Self Test & Auto Setup

At start-up the drive measures motor parameters, including the resistance and inductance, then uses this information to optimize the system performance.

General specification	
Speed Range	Up to 50 rps
Operating Temperature	0 - 40°C
Vibration Resistance	5.9m/s ² maximum
Storage Temperature	-10 - 70°C
Heat Sinking Method	Natural cooling or fan-forced cooling
Atmosphere	Avoid dust, oily mist and corrosive air
Mass	SRAC2/3SRAC2: Approx. 0.8kg
	SRAC4/SRAC8/3SRAC8: Approx. 1.2kg
Certification	RoHS , CE (EMC): EN 61800-3:2004 , CE(LVD): EN61800-5-1:2007
Features	
Idle Current	Automatic idle current reduction to reduce heat after motor stops moving for 1 second Dip switch selectable, 4 selection 25%,50%,70%,90% for SRAC4/8, 2 selection 50%,90% for SRAC2/3SRAC2
Anti-Resonance	Raises the system-damping ratio to eliminate midrange instability and allow stable operation throughout the speed range of the motor, dip switch selectable load inertia
Control Mode	Dip switch selectable Step&Dir or CW/CCW Pulse(SRAC2 和 3SRAC2 need internal jumpers)
Input Signal Filter	Digital filters prevent position error from electrical noise on command signals, Dip switch selectable 2MHz or 150KHz
Microstep Emulation	Switch selectable microstep emulation provides smoother, more reliable motion
Motor Database	Rotary switch easily selects from many popular motors
Self Test	Switch selectable automatic self test, while self test, drive will rotate the motor back and forth, two turns in each direction.
Protection	overvoltage, undervoltage, over current, motor automatic detection Open circuit
Fault Output	Optically isolated,30VDC max, 100MA max

Electrical Specifications

SRAC2

Parameter	Min.	Typ.	Max.	Unit
Power Supply	80	-	265	VAC
Output Current (Peak)	0.6	-	2.5	A
Cost current of digital input signal	6	10	15	mA
Step Frequency	2	-	2M	Hz
STEP minimum pulse width	250	-	-	ns
Direct pulse width	80	-	-	us
Under-voltage protection	-	75*/135*	-	VAC
Over-voltage protection point	-	145*/295*	-	VAC
Input Signal Voltage	4.0	-	28	V
Initialization time	-	-	2.5	S
OUT maximum output current	-	-	100	mA
OUT maximum voltage	-	-	30	V

*Note: When the AC input switch is selected on 115V, under voltage protection point is 75VAC, over voltage protection point is 145VAC. When the input switch is selected on 230V status, under voltage protection point is 135VAC, over voltage protection point is 295VAC.

SRAC8

Parameter	Min	Typ.	Max	Units
Power Supply	80	-	265	VAC
Output Current (Peak)	0.4	-	8	Amps
Cost current of digital input signal	6	10	15	mA
Step Signal Frequency	2	-	2M	Hz
STEP minimum pulse width	250	-	-	ns
Direct pulse width	80	-	-	us
Under-voltage protection	-	80	-	VAC
Over-voltage protection point	-	295	-	VAC
Input signal voltage	4.0	-	28	V
Initialization time	-	-	2.5	S
OUT maximum output current	-	-	100	mA
OUT maximum voltage	-	-	30	V

SRAC4

Parameter	Min.	Typ.	Max.	Unit
Power Supply	80	-	265	VAC
Output Current (Peak)	0.4	-	4	A
Cost current of digital input signal	6	10	15	mA
Step Frequency	2	-	2M	Hz
STEP minimum pulse width	250	-	-	ns
Direct pulse width	80	-	-	us
Under-voltage protection	-	80	-	VAC
Over-voltage protection point	-	295	-	VAC
Input Signal Voltage	4.0	-	28	V
Initialization time	-	-	2.5	S
OUT maximum output current	-	-	100	mA
OUT maximum voltage	-	-	30	V

Specification

Electrical Specifications

3SRAC2

Parameter	Min.	Typ.	Max.	Unit
Power Supply	80	-	265	VAC
Output Current (Peak)	0.6	-	2.5	A
Cost current of digital input signal	6	10	15	mA
Step Frequency	2	-	2M	Hz
STEP minimum pulse width	250	-	-	ns
Direct pulse width	80	-	-	us
Under-voltage protection	-	75*/135*	-	VAC
Over-voltage protection point	-	145*/295*	-	VAC
Input Signal Voltage	4.0	-	28	V
Initialization time	-	-	2.5	S
OUT maximum output current	-	-	100	mA
OUT maximum voltage	-	-	30	V

*Note: When the AC input switch is selected on 115V, under voltage protection point is 75VAC, over voltage protection point is 145VAC. When the input switch is selected on 230V status, under voltage protection point is 135VAC, over voltage protection point is 295VAC.

3SRAC8

Parameter	Min	Typ.	Max	Units
Power Supply	80	-	265	VAC
Output Current (Peak)	0.4	-	8	Amps
Cost current of digital input signal	6	10	15	mA
Step Signal Frequency	2	-	2M	Hz
STEP minimum pulse width	250	-	-	ns
Direct pulse width	80	-	-	us
Under-voltage protection	-	80	-	VAC
Over-voltage protection point	-	295	-	VAC
Input signal voltage	4.0	-	28	V
Initialization time	-	-	2.5	S
OUT maximum output current	-	-	100	mA
OUT maximum voltage	-	-	30	V

Input/Output

Pulse & Direction Input	EN Input	FAULT Output
<p>SRAC drive has two high-speed input port STEP and DIR, photoelectric isolation, can accept 5-24 VDC single-ended or differential signal, the highest voltage up to 28 v, falling edge signal effectively. Signal input port has a high speed digital filter, filter frequency of 2 MHz or 150 KHZ, dial the code switch is optional.</p> <p>Falling edge to the pulse signal is effective.</p> <p>Motor running direction depends on the DIR level signal, when the DIR dangling or for low electricity at ordinary times, motor clockwise; Counterclockwise DIR signal for high electricity at ordinary times, motor running.</p>	<p>The EN input enables or disables the drive amplifier. When EN input is ON the drive amplifier is deactivated. All the MOSFETs will shut down, and the motor will be free. When EN input is OFF, the drive is activated.</p> <p>A falling signal into the EN input will reset the error status and activate the drive amplifier again.</p>	<p>FAULT Output is optically isolated. The maximum collector current is 100mA, and the maximum collector to emitter voltage is 30 volts. The output can be wired to sink or source current.</p> <p>When drive is working normally, the output is open.</p>
<p>Connecting to indexer with sinking outputs</p>	<p>Connecting the input to a switch or relay</p>	<p>Connecting a sinking output</p>
<p>Connecting to indexer with sourcing outputs</p>	<p>Connecting the input to sinking outputs</p>	<p>Connecting PLC sourcing output</p>
<p>Connecting to indexer with differential outputs</p>	<p>Connecting the input to sourcing outputs</p>	<p>Connecting PLC sourcing output</p>
		<p>Driving a relay</p>

Mechanical Dimension

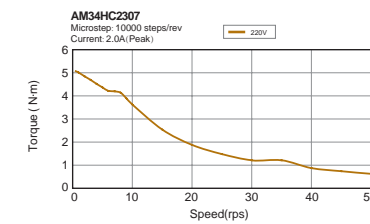
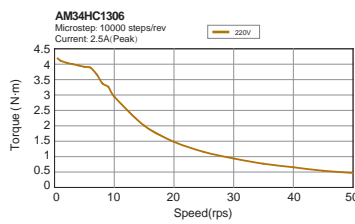
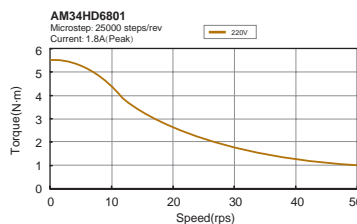
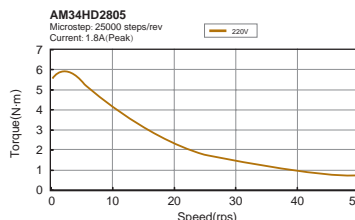
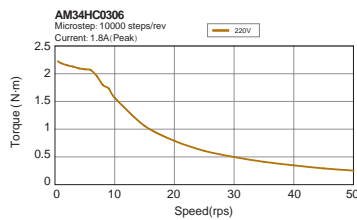
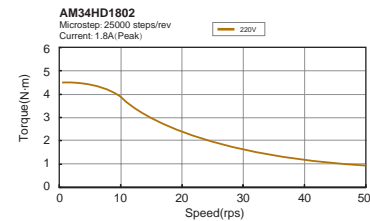
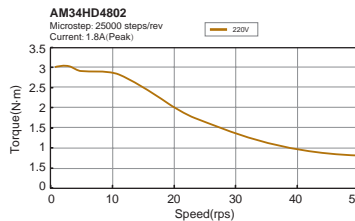
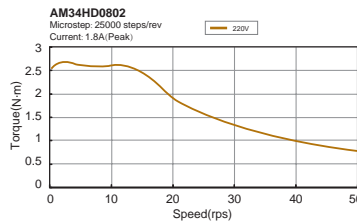
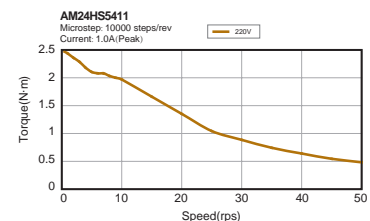
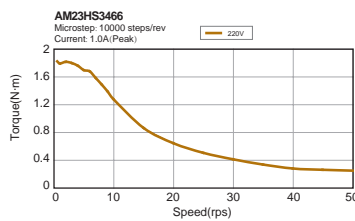
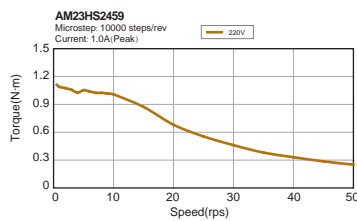
<p>SRAC2</p>	<p>Unit:mm</p>	
<p>SRAC4/8</p>	<p>Unit:mm</p>	
<p>3SRAC2</p>	<p>Unit:mm</p>	
<p>3SRAC8</p>	<p>Unit:mm</p>	

Recommended Motors

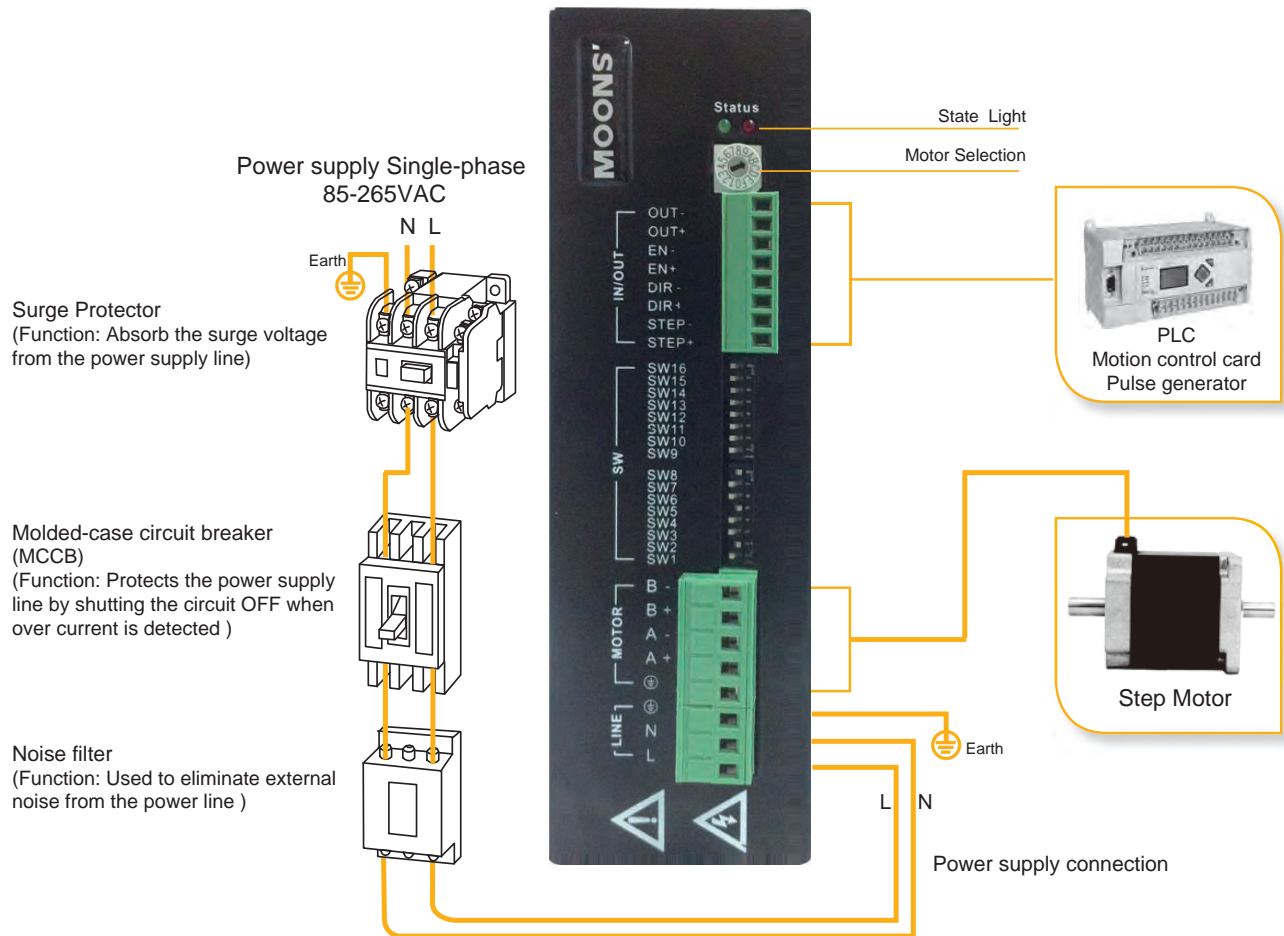
Matching Drive	Model	Shaft	Step Angle	Leads	Length	Holding Torque	Current "A"		Resistance "Ω"		Rotor Inertia G-cm ²	Motor Mass Kg	Dielectric Strength		
					Mm	N-m	Series	Parallel	Series	Parallel					
2 Phase Drive	SRAC2	AM23HS2459-01	Single Shaft	1.8	4	54	1.7	1	-	16.6	-	260	0.6	1500VAC 1 minute	
		AM23HS3466-01	Double Shaft			76	2.2			25.4	-	460	1		
		AM24HS5411-01N	Single Shaft			85	3.1			15.4	-	900	1.4		
	SRAC4 / SRAC8	AM34HD0802-01	Single Shaft		8	3.6	66.5	4.2	1.8	3.6	3.4	0.9	1100		1.6
		AM34HD0802-02	Double Shaft				75	4.7			3.6	0.9	1350		1.9
		AM34HD4802-01	Single Shaft				96	7.3			3.6	0.9	1850		2.7
		AM34HD1802-01	Single Shaft				115	7.6			4	1	2400		3.5
		AM34HD1802-03	Double Shaft								4.2	1	2750		3.8
		AM34HD6801-01	Single Shaft				125.5	8.7							
		3 Phase Drive	3SRAC2 / 3SRAC8				AM34HC0306-01	Single Shaft			1.2	3	66.5		2.5
AM34HC1306-01	Single Shaft			96	5.15	2.0	-	7	-	1850			2.7		
AM34HC2307-01	Single Shaft			125.5	5.6	2.0	-	6	-	2750			3.8		

series connection, suggest that the driving voltage 220vac ; parallel connection suggest the driving voltage 110vac

Torque Curves



System Configuration



Numbering System

SRAC - 2

Series Number

Current
2=2.5A maximum
4=4.0A maximum
8=8.0A maximum

Ordering Information

Type	Model	Current	Voltage	Selectable Microstep	Selectable Current
2 phase drive	SRAC2	0.6-2.5A	80-265VAC	16 settings	8 settings
	SRAC4	0.4-4.0A	80-265VAC		16 settings
	SRAC8	0.4-8.0A	80-265VAC		16 settings
3 phase drive	3SRAC2	0.6-2.5A	80-265VAC		8 settings
	3SRAC8	0.4-8.0A	80-265VAC		16 settings

Optional Accessories

EMF absorption module

When the motor slowdown, it will be like as a generator load kinetic energy into electrical energy. Some of the energy that will be consumed by motor drive. If your application has

High load running at high speed, the considerable kinetic energy will be converted into electricity. Linear power supply usually simple with a large capacitor to absorb the energy without the system

Damage. Switching power supply is often off the excess energy back to the drive in an overvoltage condition, damage may be caused by drive. In order to prevent this kind of feeling

The drive side of the port in Regen R+, R- end to increase the use of our company provide the power 50W 40 ohm EMF absorption power resistor.

Note: 40 ohm resistor power below 50 w shall not be used, otherwise the damage resistance is prone to overheating. And Regen drive for high pressure port, the connection device must be broken Electricity, and pay attention to the leakage protection to prevent damage to people and equipment.



SHANGHAI AMP&MOONS' AUTOMATION Co.,LTD.

No. 168 Mingjia Road Industrial Park North
Minhang District Shanghai 201107, P.R. China
Tel: +86(0)21-5263 4688
Fax: +86(0)21-6296 8682
Web: www.moonsindustries.com
E-mail: ama-info@moons.com.cn

 **Service Center**
400-820-9661



Distributors for Australia & New Zealand

MOTION TECHNOLOGIES PTY LIMITED

24/22-30 Northumberland Road
Caringbah NSW 2229 Australia
Phone: (02) 9524 4782

sales@motiontech.com.au
www.motiontech.com.au

© 10/07/2023



MOONS'
moving on better way